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24. CHAPTER 2. E2.4.

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Systems. Since $R(s) = 1/s$, we have. $Y(s) = \frac{6}{s(s+30)(s+10)}$

The partial fraction
expansion of $Y(s)$ is
given by $A_1/s + A_2/(s+30) + A_3/(s+10)$
 $= \dots$

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~~Katsuhiko ...~~

Most modern PID controls in industry are implemented as computer software in distributed control systems (DCS), programmable logic controllers (PLCs), or discrete compact

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analog controllers.

Electronic analog PID
control loops were often
found within more
complex electronic
systems, for example,
the head positioning of a
disk drive, the power
conditioning of a power
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With modern computer
control systems, scaling
for unit conversions is
becoming more
common in the
controller signal path.
Sometimes a display has

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been scaled but the signal in the loop path has not. You must pay attention to this detail and make sure you are using the correct units in your computations. There is more discussion in this article.

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