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and guidelines for the inherent safe design, protective measures and information for use of industrial robots. It describes basic hazards associated with robots and provides requirements to eliminate, or adequately reduce, the risks associated with these hazards.

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10218-1. Second edition.  
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industriels ?

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ISO 10218 has been  
created in recognition of  
the particular hazards  
that are presented by  
industrial robots and  
industrial robot systems.

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This part of ISO 10218 is  
a type-C standard as  
outlined in ISO 12100.

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Edition, July 1, 2011 -  
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requirements for  
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While the ISO 10218 -  
Robots and Robotic

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Devices Safety Package is specific to industrial robots, it is a comprehensive collection that provides the design, manufacturing, installation, operation, maintenance - and if necessary - the decommissioning of an industrial robot system. The package includes:  
ISO 10218-1:2011 ISO



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Robotic Package enables  
a space within the  
collaborative  
environment where the  
robot system (including

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the work piece) and a human can perform tasks concurrently during production operation.

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Collaborative Robots  
ISO 10218-2:2011  
describes the basic  
hazards and hazardous  
situations identified with  
these systems, and  
provides requirements to  
eliminate or adequately  
reduce the risks  
associated with these  
hazards. ISO  
10218-2:2011 also  
specifies requirements for  
the industrial robot

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system as part of an  
integrated manufacturing  
system.

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industrial robots - Part 1:  
Robots (ISO  
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Standard) This part of  
ISO 10218 specifies  
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guidelines for the  
inherent safe design,  
protective measures and



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information for use of  
industrial robots.

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' International  
Standard ' shall be read  
as ' Singapore  
Standard ' . 2. Where  
applicable, the references  
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Standards shall be  
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July 1, 2011 - Robots and robotic devices - Safety requirements for industrial robots - Part 2: Robot systems and integration This part of ISO 10218 specifies safety requirements for the integration of industrial robots and industrial robot systems as defined in ISO 10218-1, and industrial robot cell(s).

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R15.06. • 1999 R15.06  
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and requirements for  
systems (with end-

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