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the voltage by the armature current to get the power gives the following relationship: $P = EI = VI - I^2 R$. It shows that the mechanical power delivered by the motor is equal to the back EMF times the armature current OR the

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Electrical power applied to the
motor less the $I^2 R$ losses in the
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SOLUTION ...

In the third part, electrical drives

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are discussed, combining the traditional (rotating field and DC commutator) electrical machines treated in the first part and the power electronics of part two. Field orientation of induction and synchronous machines are discussed in detail, as well as

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rotating electrical machines.

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and a sophisticated control system that controls the rotation of the motor shaft. Now days, this control can be done easily with the help of software.

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