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courses. There is no central location for these, so we have collated some resources below. Bear in mind that course syllabuses evolve over time, and different lecturers structure their courses differently and

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choose their own notation conventions.

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$1 = r \cos(\theta) \cos(\phi) + c$ where
we have used the formula \cos

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$A \cos B - \sin A \sin B = \cos(A + B)$ Differentiating again and simplifying as before, $y. 2 = r^2 e^{ax} \cos(\theta + bx + c)$. Similarly $y. 3 = r^3 e^{ax} \cos(\theta + bx + c)$.
..... Thus $y = r^n e^{ax} \cos(\theta + bx + c)$

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Where $r = \sqrt{a^2 + b^2}$ and $\theta = \tan^{-1}(b/a)$.

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It is important to note that

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$$[T(x)]_{B_2} = T[B_1, B_2] [x]_{B_1}.$$

That is, we multiply the matrix of the linear transformation with the coordinates $[x]_{B_1}$, of the vector $x \in V$ to obtain the coordinates of the vector $T(x) \in W$.

3. If A is an

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$m \times n$ matrix, then A induces a
linear transformation T_A :
 $\mathbb{R}^n \rightarrow \mathbb{R}^m$, defined by $T_A(x) = Ax$.

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